



Module (Course Syllabus) Catalogue 2023-2024

College/ Institute	Erbil Technology College	
Department	Petroleum Technology	
Module Name	Measurement & Process Control I	
Module Code	MPC303	
Semester	Third	
Credits	6 ECTS	
Module type	Prerequisite <input type="checkbox"/>	Core <input type="checkbox"/> Assist. <input type="checkbox"/>
Weekly hours	4	
Weekly hours (Theory)	(2)hr Class	(75)hr Workload
Weekly hours (Practical)	(2)hr Class	(75)hr Workload
Lecturer (Theory)	Brzo Aziz Qadir	
E-Mail & Mobile NO.	Brzo.qadir@epu.edu.iq	
Lecturer (Practical)	Brzo Aziz Qadir	
E-Mail & Mobile NO.	Brzo.qadir@epu.edu.iq	

Course Book

<p>Course Description</p>	<p>This course offers a more advanced discussion of control systems, introducing many modern control techniques, and implementation issues. In particular, students who successfully complete this course should have:</p> <ul style="list-style-type: none"> • an exposure to modern control tools (e.g., observers, state variable feedback, internal model control) • a basic understanding of various factors which limit the achievable control system performance (e.g., time delays, non minimum phase zeros) • experience in several lab implementations of control systems • initial exposure to various control implementation issues (e.g. Sampled data systems, Actuator saturation, Anti-windup schemes) • an initial exposure to more advanced topics (e.g., multivariable systems, pole assignment) • some knowledge of various case studies of successful modern control implementations • introduction to empirical modelling and system identification
<p>Course objectives</p>	<p>The aim of the course is to give an introduction to the control system analysis and design.</p> <p>The purpose of the course is to introduce the nature of nonlinearities found in control systems both in the forward path and in the feedback path. Some times nonlinearities may be used to adjust the performance of the system. Students are expected to learn why standard methods of analysis and design in linear systems are not applicable in nonlinear system. Methods suitable for nonlinear systems are introduced and their applications are explored.</p> <p>An ability to apply knowledge of mathematics, science, and engineering</p> <p>An ability to design a system, component, or process to meet desired needs within realistic constraints such as economic, environmental, social, political, ethical, health and safety, manufacturability, and sustainability.</p> <p>.</p>
<p>Student's obligation</p>	<p>The presence of students in both lectures and Lab will have additional credit .He /She is required to continuously follow the lectures ,Submits homework and reports .Anticipate Tests or quizzes any time in Class or Lab.</p>
<p>Required Learning Materials</p>	<p>Psychics ,Chemistry and Math .</p>
<p>Assessment scheme</p>	<p>16% Mid Term (Theory and practical) 4% Quiz 40% Assignment (report, paper, homework, seminar..)</p>

	25% final practical 15% final theory	
Specific learning outcome:	1-Understanding of the essentials of Control system. 2- Understanding of the essentials of using Mtlab program in Control System. 3- Understanding of the essentials of Modeling and design of Control System. 4- The ability of a student use simulation program. 5-Using simulation program for experiment will be done in Lab.	
Course References:	R.C. Dorf, Modern Control Systems, Addison-Wesley, 5th (1989) or any later edition. J.J. D'Azzo and C.H. Houpis, Linear Control System Analysis and Design, McGraw-Hill, 3rd (1988) or any later edition. Ogata, K., Modern Control Engineering, Prentice-Hall, [2002] Hsu, J. C. & A. U. Meyer, Modern Control Principles and Applications, McGraw-Hill, [1968]	
Course topics (Theory)	Week	Learning Outcome
Introduction: definition and classification of systems, control systems.	1	Define control system
Open Loop control System	2	Learn property of open loop control system
Closed loop control system	3	Learn property of closed loop control system
Comparison closed loop & open loop control system	4	Distinguish open loop and closed loop control system
Water control system.	5	Given application of open loop control system
Liquid Level Control System	6	Given application of closed loop control system

Feed back : Closed system to control the pressure	7	Solve the practical examples
Room Temperature control system	8	Explain
Feedback connection	9	Given the types of connection.
Time response control system	10	Draw the block diagram.
Basic rules with block diagram transformation	11	Determine the calculation for block diagram control system
Find transfer function for feedback control system	12	Solving examples
Practical Topics	Week	Learning Outcome
Introduction and Control Basics Matlab software	1	Introduction of Matlab
Variable assignment	2	Represented variables.
Scalar, Vector and Matrix: Basic Operation.	3	Solve examples.
Useful matrix operations Determinant :det(m), Inverse :inv(m), Rank: rank(m), I by j matrix of m= Zeros :zeros(I,j), I by j of matrix of ones :m=ones(I,j), I by j of matrix of :m=eye(i).	4	Learn Application of matrices.
Graphics: Basic 2-D Plots, Specialized 2-D plots	5	Learn plotting variables.
Using Matlab to create models	6	How build model
• Why model? - Represent - Analyses	7	Using model for solving problems

• What kind of systems are we interested?	8	Application on feedback system.
- Single-Input-Single-Output (SISO)	9	Determination of response
Response of second order control system	10	Solving second order examples
Find response of feedback control system	11	Find overall output response

Extra notes:

I will assess the students continuously through their activities in the class. Any student with thoughts about learning, and suggestions of different way of dealing with difficulties and problems will be very welcomed.

Showing relevant laboratory equipment, technical videos, and other academic activities are part of the course model.

External Evaluator

General evaluation of course objectives and content.

General evaluation of lectures/ Practical sessions.

General evaluation of lecturer.

Instructor: :Lecturer Brzo A.Qadir